

Residual Information for Absolute Model Fit

Feb 2020

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- I hope we can improve on this by approaching model fit differently.

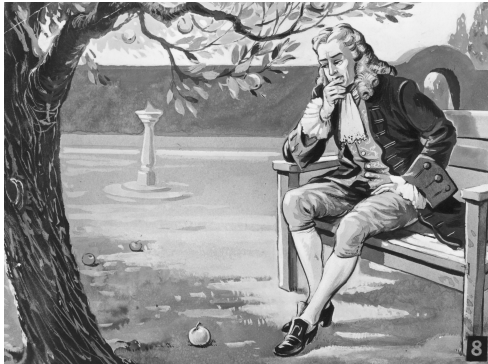


Model fit – simple, deterministic



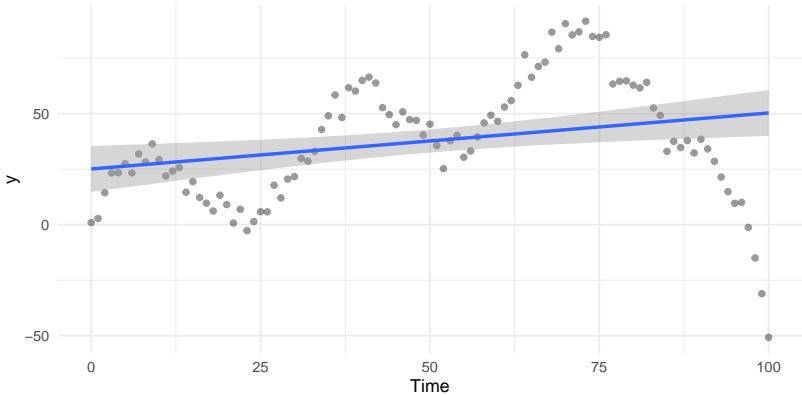


- Straightforward with simple, deterministic systems and yes / no questions
– prediction errors that can't be explained by instrumentation imply the model is inadequate.



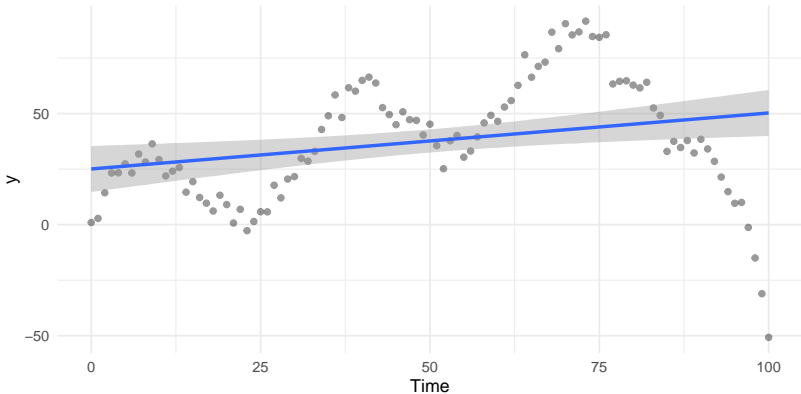


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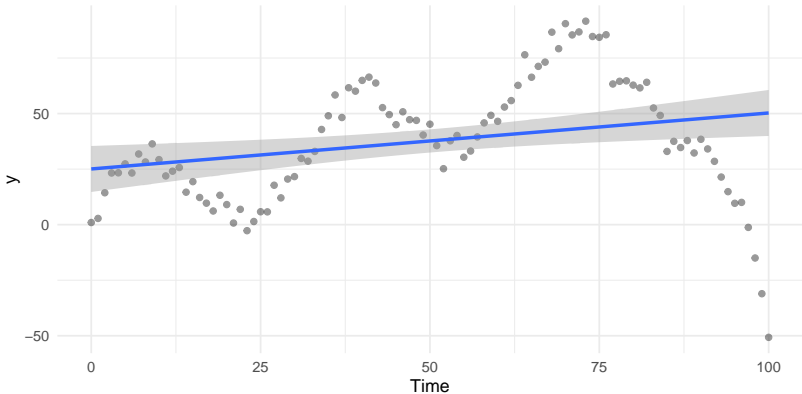


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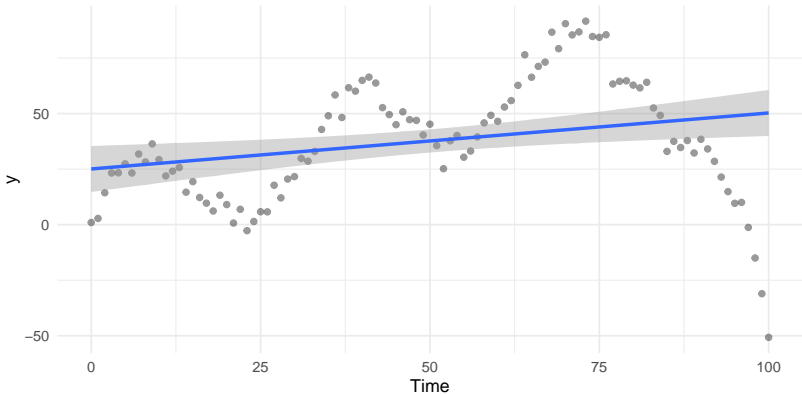


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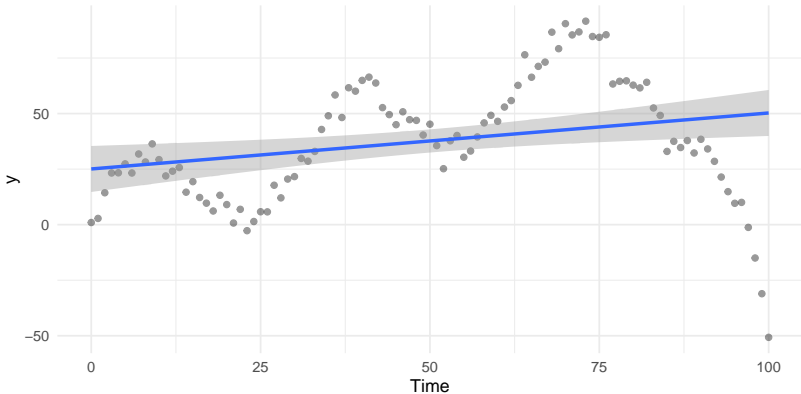


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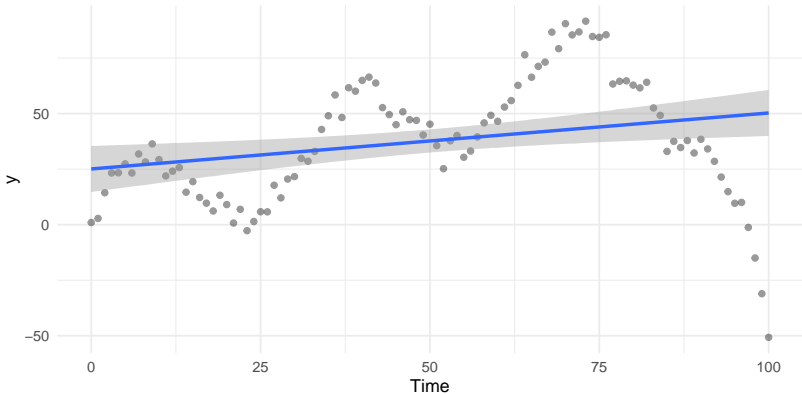


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 - Bad predictions for new data in some conditions.
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 - Interpreted loosely, it leads to crazy inferences.
 - Uncertainty about the parameter tells us nothing about the 'trueness' of the parameter.

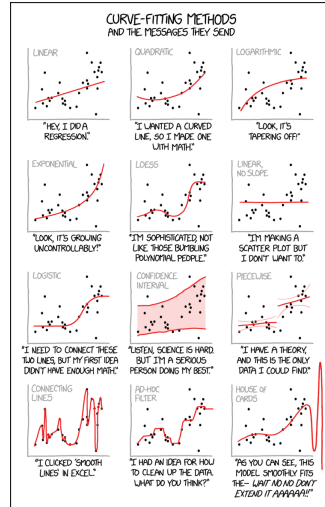




How to quantify model fit then?

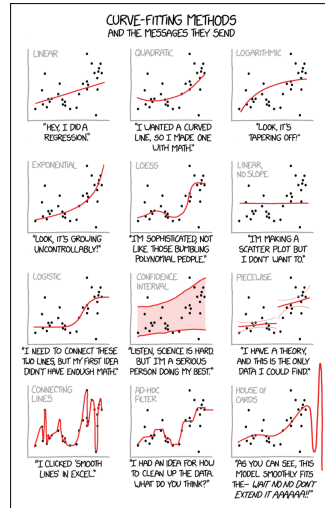


- Lots of technical concerns, but at base:



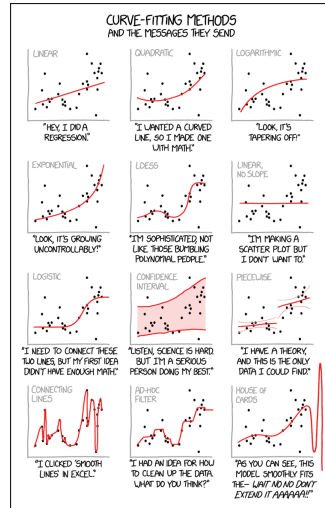


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- Lots of technical concerns, but at base:
 - How well does the fitted model predict new data?
 - How well do alternative models predict new data?





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- Theory based:



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- Data based:
 - Arbitrary 'standard' model – e.g. saturated covariance matrix.

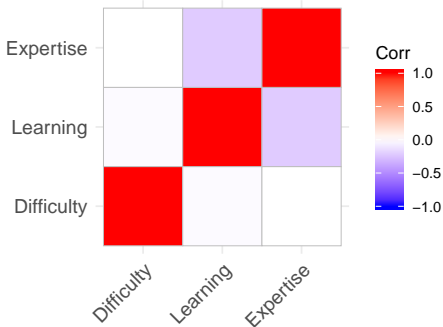


Saturated covariance as fit



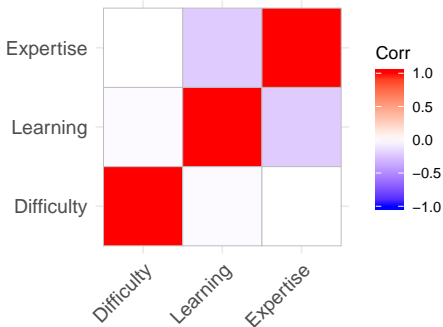


- Take some structuring of data.



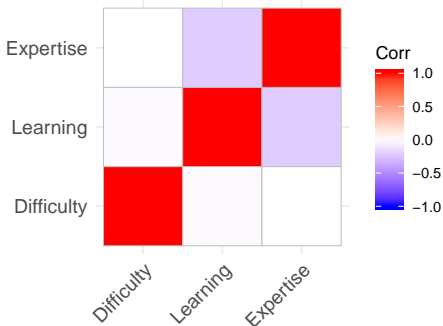


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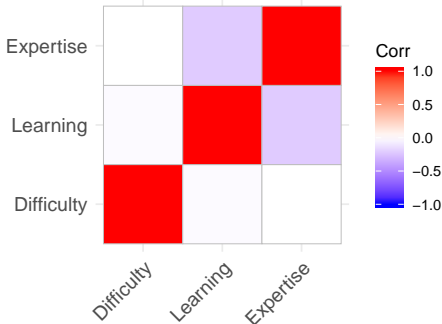


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- Compare saturated model with our model – obtain estimate of distance from saturated model.



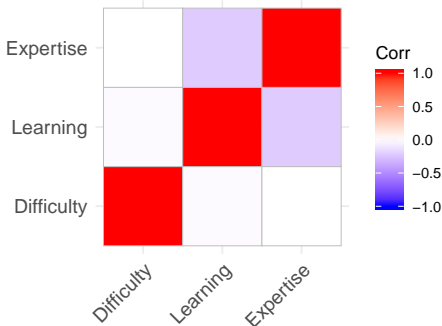


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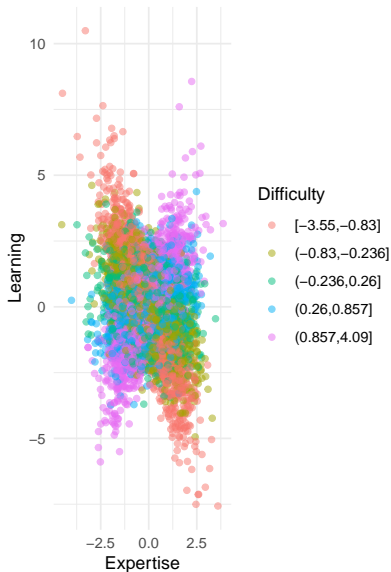
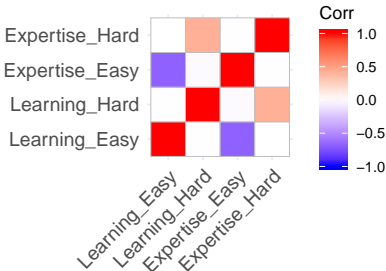
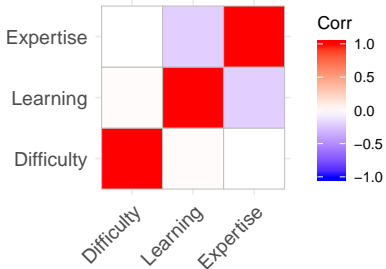
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- Compare saturated model with our model – obtain estimate of distance from saturated model.
- If the true model can be represented by some covariance matrix of our data structure, we have estimate of distance from true model.
- Otherwise, we just have estimate of distance from best linear model given our arbitrary data structuring.





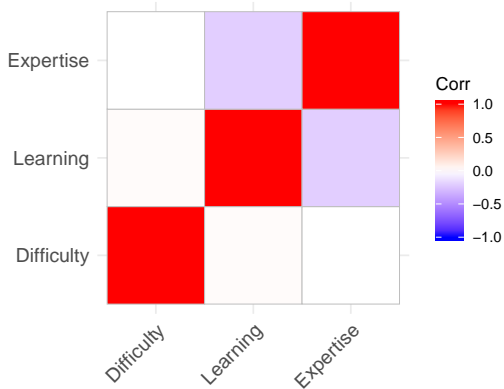
My data structure? Arbitrary!?





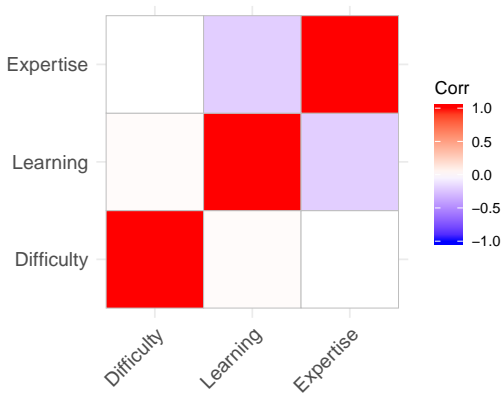


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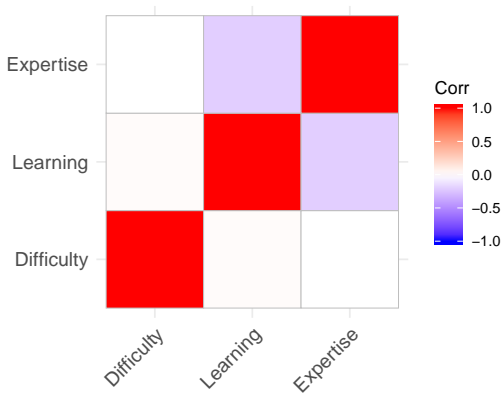


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- Can we do better?



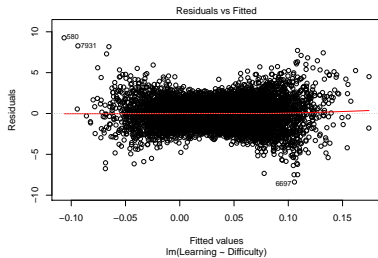
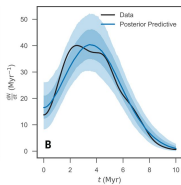
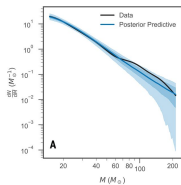


Alternative approaches:



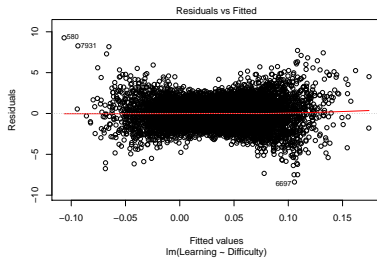
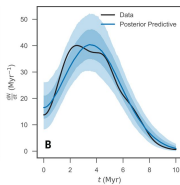
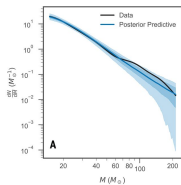


■ Posterior predictive checks:



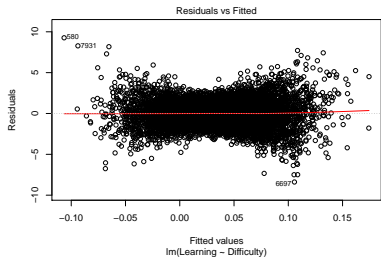
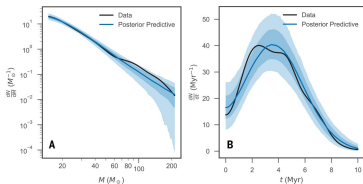


- Posterior predictive checks:
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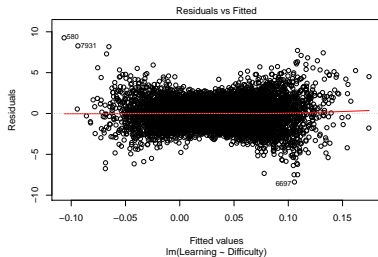
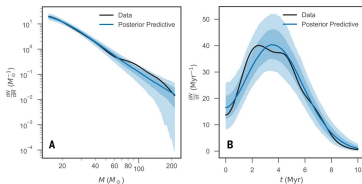


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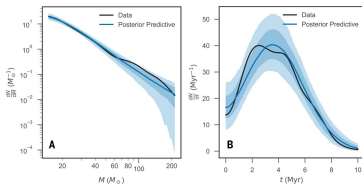


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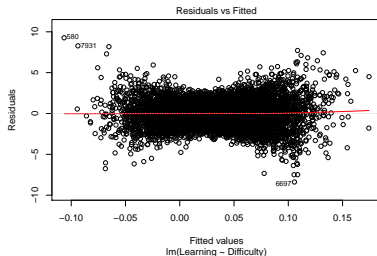




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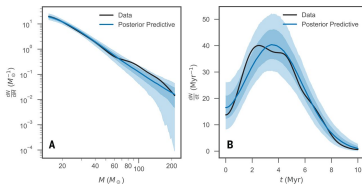


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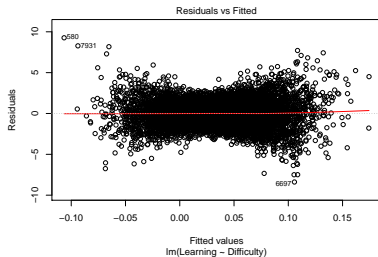




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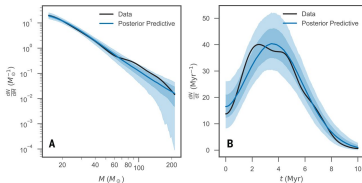


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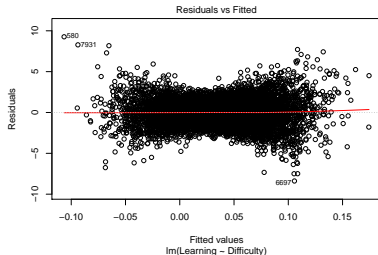




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- Residual checks:
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 - Useful, good guide to improving model, but: non-general, too much of an art, typically univariate.



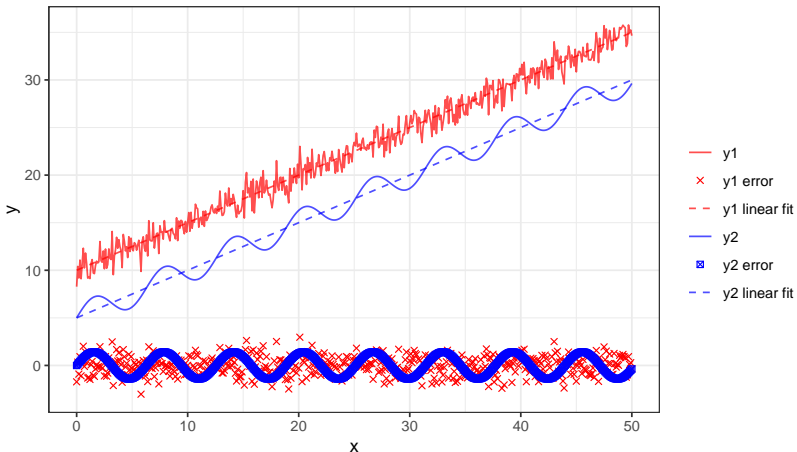


New? idea – residual information criteria



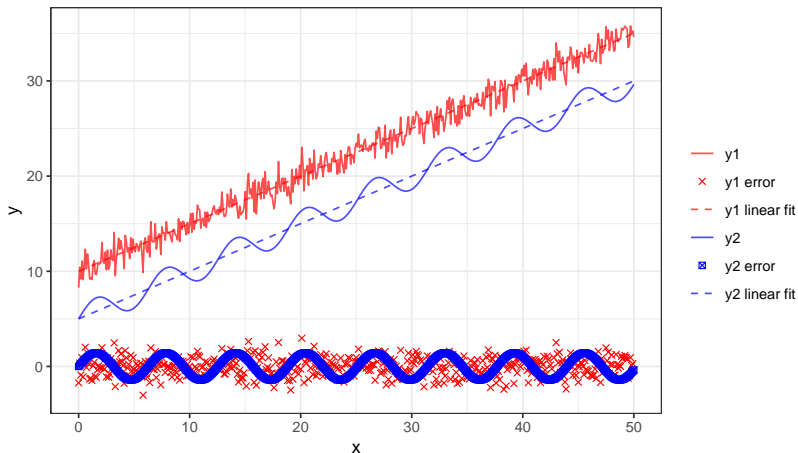


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- If we knew and fit the true / best model, residuals will be random – contain no information wrt our data.
- Therefore, information that our residuals do contain, can be used to quantify distance from best possible model.





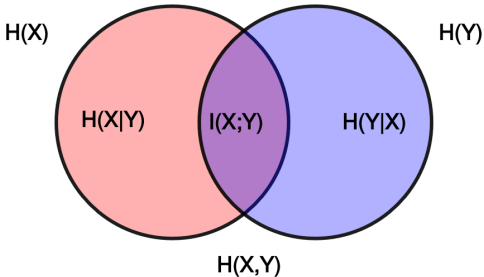
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- Need some general function to detect and quantify structure in data.

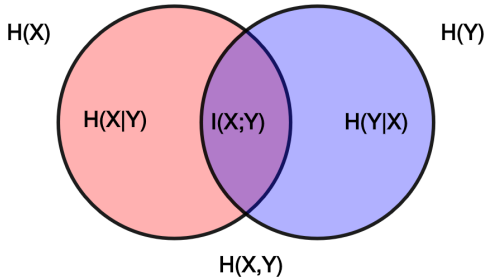


- Shannon differential entropy, H , is a scale dependent measure of information content of a variable – negative expectation of log probability.



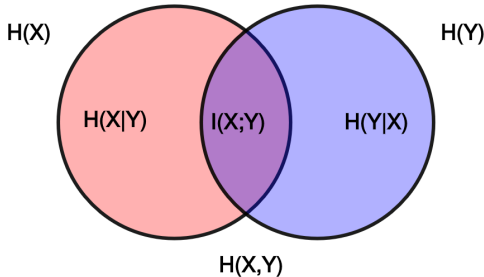


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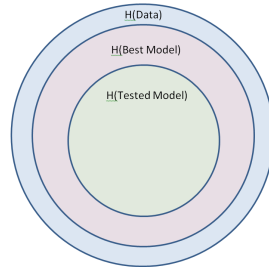
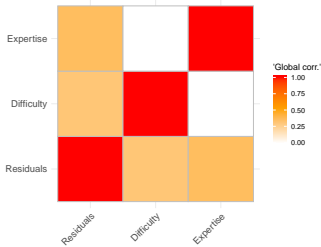
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- Conditional entropy, $H(X|Y) = H(X) - I(X, Y)$, quantifies information unique to X with respect to Y .





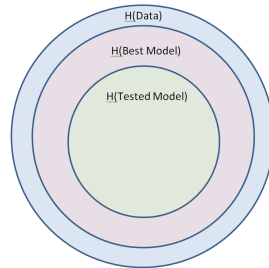
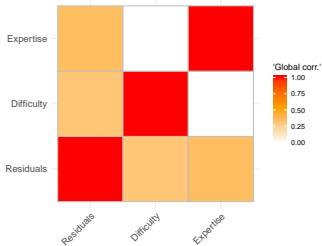


- Mutual information (nonlinear covariance) between residuals, expectations, and any additional covariates.



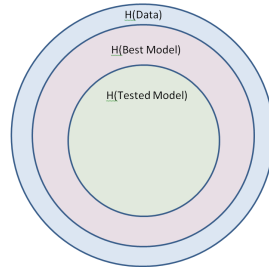
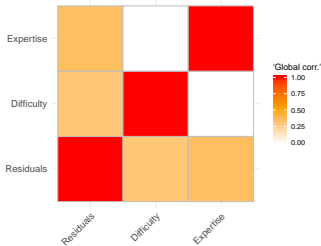


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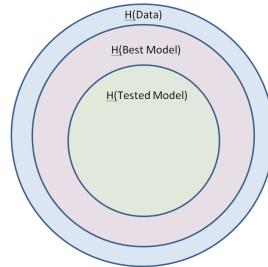
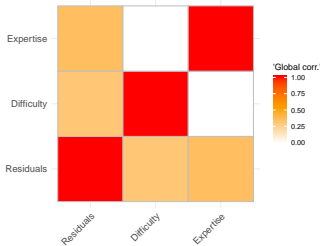


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 - Where there is shared information between data and residuals – model can be improved.





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- Overfitting can be handled either by overfitting baseline estimates in a similar fashion, or cross validation.



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- Current plan: R software to provide fit / diagnostics for arbitrary statistical model.



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 - Helps bridge some of the performance divide between prediction oriented and explanation oriented approaches.